

REVIEW

Explainable Engineering Monitoring and Low-Altitude Safety

Abstract

This review examines explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety through an evidence-centered design lens. The analysis asks how explanations should change an engineering action. It treats the relevant unit as a complete pathway from data or physical observations to representation, model output, human interpretation, and accountable action. The cited literature is synthesized without inventing experiments or unreported performance values. Particular attention is given to salience maps being treated as physical mechanisms. The review argues that credible translation requires explicit evidence boundaries, uncertainty-aware evaluation, author-visible traceability, and a documented route for intervention. The resulting framework supports condition monitoring and autonomous safety while distinguishing component promise from system readiness.

Keywords: artificial intelligence, materials, uav

1. Introduction

Research on explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety often begins with a high-performing component, yet practical value depends on the surrounding evidence chain. A component may be technically plausible and still be unsuitable for deployment if its inputs are poorly specified, its validation endpoint is misaligned with the decision, or its uncertainty is hidden from the person expected to act. The central question in this review is therefore how explanations should change an engineering action.

The analysis is structured as a narrative synthesis. It does not pool effect sizes or claim new empirical results. Instead, it compares how the cited studies define inputs, mechanisms, outputs, and evaluation conditions. This approach is especially important where salience maps being treated as physical mechanisms. A defensible review must keep source-specific findings separate from broader design implications.

2. Mechanisms and Representation Choices

Mechanistic clarity begins with an explicit system boundary. For computational systems, that boundary includes data collection, representation, training objective, inference, and user action. For physical or biomedical systems, it includes material or biological state, measurement process, intervention, and outcome. In both cases, a claim should identify what changed, under which conditions, and how the change was observed.

Han et al. (2026) propose user-guided embeddings for fast diversified top-k rule discovery. Within the present review, this source functions as mechanism-level evidence for explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety. Its contribution is bounded to the mechanism, dataset, or decision setting that it directly addresses; it is not treated as proof of performance in condition monitoring and autonomous safety. This separation keeps the evidential claim traceable while still allowing comparison across methods.

Deng et al. (2025) use curriculum reinforcement learning to improve vision-language generalization and reasoning. Within the present review, this source functions as mechanism-level evidence for explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety. Its contribution is bounded to the mechanism, dataset, or decision setting that it directly addresses; it is not treated as proof of performance in condition monitoring and autonomous safety. This separation keeps the evidential claim traceable while still allowing comparison across methods.

Vaswani et al. (2017) establish the attention-based architecture underlying modern sequence models. Within the present review, this source functions as mechanism-level evidence for explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety. Its contribution is bounded to the mechanism, dataset, or decision setting that it directly addresses; it is not treated as proof of performance in condition monitoring and autonomous safety. This separation keeps the evidential claim traceable while still allowing comparison across methods.

Bengio et al. (2009) frame training order as a controllable learning variable. Within the present review, this source functions as mechanism-level evidence for explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety. Its contribution is bounded to the mechanism, dataset, or decision setting that it directly addresses; it is not treated as proof of performance in condition monitoring and autonomous safety. This

separation keeps the evidential claim traceable while still allowing comparison across methods.

The comparison suggests that representation choices are not neutral preprocessing steps. They determine which variations become visible, which are compressed away, and which forms of uncertainty can reach the decision interface. Reviewers should therefore ask whether the representation preserves the distinctions that matter for the intended use.

3. Evaluation and Error Analysis

Evaluation should follow the decision pathway rather than stop at a single technical score. A layered plan covers analytical validity, robustness under plausible variation, calibration, decision utility, and post-deployment monitoring. Aggregate metrics should be supplemented with error categories that reveal where and why performance changes.

Feng and Xu (2025) use texture synthesis and explainable AI to inform periodic metamaterial design. Within the present review, this source functions as evaluation evidence for explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety. Its contribution is bounded to the mechanism, dataset, or decision setting that it directly addresses; it is not treated as proof of performance in condition monitoring and autonomous safety. This separation keeps the evidential claim traceable while still allowing comparison across methods.

Xu and Jin (2025) organize urban low-altitude safety into rerouting, detect-and-avoid, and recovery stages. Within the present review, this source functions as evaluation evidence for explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety. Its contribution is bounded to the mechanism, dataset, or decision setting that it directly addresses; it is not treated as proof of performance in condition monitoring and autonomous safety. This separation keeps the evidential claim traceable while still allowing comparison across methods.

Jardine, Lin, and Banjevic (2006) connect condition monitoring to maintenance decisions. Within the present review, this source functions as evaluation evidence for explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety. Its contribution is bounded to the mechanism, dataset, or decision setting that it directly addresses; it is not treated as proof of performance in condition monitoring and autonomous safety. This separation keeps the evidential claim traceable while still allowing comparison across methods.

For condition monitoring and autonomous safety, errors are asymmetric. A false alarm, missed event, unstable ranking, or unsafe action does not carry the same consequence. Thresholds and abstention rules should therefore be justified against the operating context, not selected solely for benchmark convenience.

4. Translation, Governance, and Use Conditions

Translation requires evidence that the tested conditions resemble the intended environment closely enough for the decision at hand. Dataset shift, population differences, material variability, sensor degradation, and changing policy definitions can all break that link. A release decision should state its validity conditions and identify triggers for revalidation.

Parziale et al. (2026) combine data fusion and explainable convolutional networks for rotating-shaft monitoring. Within the

present review, this source functions as translation evidence for explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety. Its contribution is bounded to the mechanism, dataset, or decision setting that it directly addresses; it is not treated as proof of performance in condition monitoring and autonomous safety. This separation keeps the evidential claim traceable while still allowing comparison across methods.

Tao, Lyu, and Cao (2026) present a deep-learning framework for automated platform content moderation. Within the present review, this source functions as translation evidence for explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety. Its contribution is bounded to the mechanism, dataset, or decision setting that it directly addresses; it is not treated as proof of performance in condition monitoring and autonomous safety. This separation keeps the evidential claim traceable while still allowing comparison across methods.

Beard and McLain (2012) integrate guidance, estimation, control, and planning for small unmanned aircraft. Within the present review, this source functions as translation evidence for explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety. Its contribution is bounded to the mechanism, dataset, or decision setting that it directly addresses; it is not treated as proof of performance in condition monitoring and autonomous safety. This separation keeps the evidential claim traceable while still allowing comparison across methods.

Governance is part of the technical architecture because it assigns authority and creates recoverable records. Useful controls include versioned data and models, decision logs, review rights, escalation paths, and change-management thresholds. These controls are most effective when each is tied to a named hazard rather than a general aspiration.

5. Research Priorities

Future studies should predefine the intended decision, measure uncertainty at the point where it affects action, and report failure modes alongside average performance. Comparative work should use baselines that expose the value of each added component. External validation should test meaningful shifts rather than repeat a near-identical sampling process.

Evidence packages should also preserve provenance. A reader should be able to identify which source supports each mechanism, evaluation choice, and governance recommendation. This requirement improves scientific clarity and prevents a densely cited paragraph from implying that every reference supports every claim.

6. Conclusion

The literature supports a disciplined pathway for reviewing explainable monitoring across rotating machinery, metamaterial design, and low-altitude safety: define the decision, preserve evidence boundaries, test consequential error modes, and connect uncertainty to action. The strongest contribution of a review is not a universal ranking but a transparent account of what is known, what remains conditional, and what would justify the next stage of use in condition monitoring and autonomous safety.

References

- Beard, R. W., & McLain, T. W. (2012). *Small unmanned aircraft: Theory and practice*. Princeton University Press.
- Bengio, Y., Louradour, J., Collobert, R., & Weston, J. (2009). Curriculum learning. In *Proceedings of the 26th International Conference on*

Machine Learning (pp. 41-48).

- Deng, H., Zou, D., Ma, R., Luo, H., Cao, Y., & Kang, Y. (2025). Boosting the generalization and reasoning of vision language models with curriculum reinforcement learning. *arXiv preprint arXiv:2503.07065*.
- Feng, Z., & Xu, H. (2025, August). Textures Synthesis-Based XAI Approach for Designing Periodic Metamaterials Inspired by Stochastic Microstructures. In *International Design Engineering Technical Conferences and Computers and Information in Engineering Conference* (Vol. 89237, p. V03BT03A001). American Society of Mechanical Engineers.
- Han, Z., Chen, W., Han, Y., Mao, R., & Qin, J. (2026). Fast diversified top-k rule discovery via user-guided embeddings. *IEEE Transactions on Knowledge and Data Engineering*, 38, 1739–1753.
- Jardine, A. K. S., Lin, D., & Banjevic, D. (2006). A review on machinery diagnostics and prognostics implementing condition-based maintenance. *Mechanical Systems and Signal Processing*, 20(7), 1483-1510. <https://doi.org/10.1016/j.ymssp.2005.09.012>
- M. Xu and M. Jin, "Three-Stage Urban Low-Altitude Safety: Dynamic Geo-Fencing Rerouting + Remote ID/ADS-B Based Detect-and-Avoid + Power Failure/Crash Recovery," 2025 Low-Altitude Economy Forum & International Conference on Low-Altitude Flight Technology and Unmanned Aerial Vehicle Application (LEF & ICLU), Guangzhou, China, 2025, pp. 164-168, doi: 10.1109/LEFICLU65987.2025.11297342.
- Parziale, M., Yeung, Y. F., Youcef-Toumi, K., Giglio, M., & Cadini, F. (2026). Anomaly characterization for the condition monitoring of rotating shafts exploiting data fusion and explainable convolutional neural networks. *Structural Health Monitoring*, 25(3), 1678–1698.
- Tao, J., Lyu, R., & Cao, X. (2026). A Deep Learning-Based Automated Content Moderation Framework for Online Platforms. *Future-Adaptive Intelligence and Lifelong Systems*, 1(1).
- Vaswani, A., Shazeer, N., Parmar, N., Uszkoreit, J., Jones, L., Gomez, A. N., Kaiser, Ł., & Polosukhin, I. (2017). Attention is all you need. *Advances in Neural Information Processing Systems*, 30.